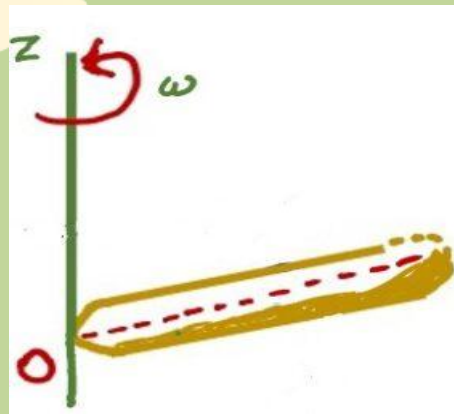


Relation between Angular and Linear Velocities

In this article, we will discuss the relation between angular and linear velocities. The rate of change of angular displacement is called angular velocity. And the rate of change of linear displacement is called linear velocity.

Consider a rigid body rotating about the z-axis with an angular velocity ω along a circle of radius 'r'. The point P moves along a circle with a linear velocity V but the line OP rotates with angular velocity ω .

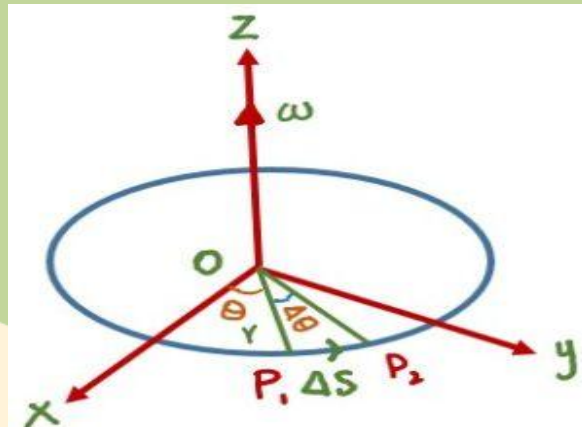


As the axis of rotation is fixed, the direction of ω remains the same and so can be considered as a scalar.

Similarly, we only considered the magnitude of linear velocity which is also treated as a scalar.

Relation between angular and linear velocities:

Consider the motion of point P along the circle. Let point P moves through distance $P_1P_2 = \Delta s$ in time interval Δt . Then the reference line OP has an angular displacement $\Delta\theta$ radian in that time interval Δt .



Then by relation

$$\Delta s = r \Delta\theta$$

Dividing the both sides by Δt and applying limit $\Delta t \rightarrow 0$

$$\lim_{\Delta t \rightarrow 0} \frac{\Delta s}{\Delta t} = r \lim_{\Delta t \rightarrow 0} \frac{\Delta\theta}{\Delta t}$$

$$\mathbf{V} = r\omega$$

Where v is the velocity of point P and ω is the angular velocity of reference line OP.

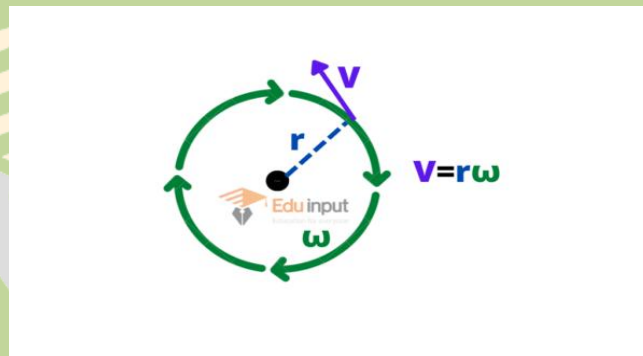
In the limit, $\Delta t \rightarrow 0$ the length of arc P_1P_2 becomes very small and its direction is tangent to the circle at point P1.

Thus the magnitude of velocity when moving along the circle is V but its direction is tangent to the circle. That is why the linear velocity of point P is also known as tangential velocity.

Where v is the velocity of point P and ω is the angular velocity of reference line OP .

In the limit $\Delta t \rightarrow 0$ the length of arc P_1P_2 becomes very small and its direction is tangent to the circle at point P_1 .

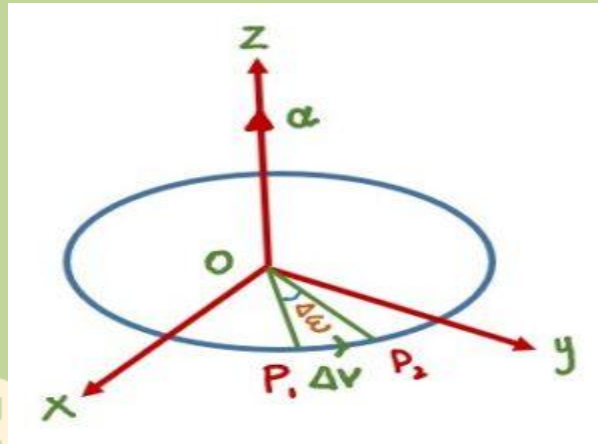
Thus the magnitude of velocity when moving along the circle is V but its direction is tangent to the circle. That is why the linear velocity of point P is also known as tangential velocity.



Angular velocity	Linear Velocity
The rate of change of angular displacement is called angular velocity	The rate of change of linear displacement is called linear velocity
In a circular motion, the angular velocity of a particle is along the axis of a circle.	In a circular motion, the linear velocity of a particle is along the circumference of a circle.
Angular velocity remains the same in a circle.	Linear velocity changes at every point in the circle.
The Units of Angular velocity are degree and radian.	The Unit of linear velocity is m/s.
Angular velocity is represented by ω	Linear velocity is represented by v

Relation between Linear and Angular Acceleration:

When the reference line OP is rotating with an angular acceleration α the point P will also have a linear or tangential acceleration a_t .



Let the change in linear velocity is Δv and the change in angular velocity be $\Delta\omega$ in time interval Δt when the body is rotating along a circle.

Thus

$$\Delta v = r\Delta\omega$$

Dividing by Δt and applying the limit $\lim_{\Delta t \rightarrow 0}$ we have

$$\lim_{\Delta t \rightarrow 0} \Delta v / \Delta t = r \lim_{\Delta t \rightarrow 0} \Delta\omega / \Delta t$$

$$a_t = r\alpha$$

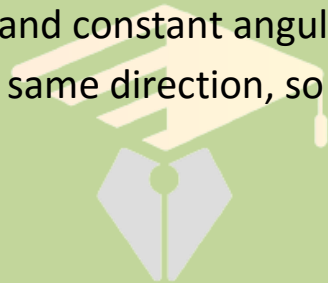
From equations $v = r\omega$ and $a_t = r\alpha$ it is clear that for a rotating body the points at different distances from the axis of rotation do not have the same speed or acceleration. But all points have the same angular displacement, angular speed, and angular accelerations.

Equations of Angular Motion:

Linear(a = constant)	Angular($\alpha = \text{constant}$)
$V_f = v_i + at$	$\omega_f = \omega_i + \alpha t$
$S = v_i t + 1/2 at^2$	$\theta = \omega_i t + 1/2 \alpha t^2$
$2as = v_f^2 - v_i^2$	$2\alpha \theta = \omega_f^2 - \omega_i^2$

The equations of angular motion are exactly the same as those in linear motion except that θ , ω , and α are replaced by s , v , and a respectively.

These angular equations of motion are only valid for fixed axes of rotation and constant angular acceleration. Since all angular vectors have the same direction, so they can be considered scalars.



Eduinput
Education for everyone